# Machine learning for graphs and with graphs Graph kernels

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#### Kernels in Machine Learning

A bit of kernels theory Back to machine learning: the representer theorem

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#### Kernels for structured data

Basics of graphs-kernels Focus on Weisfeler-Lehman Kernel Conclusion Some slides adapted from those of Jean-Philippe Vert and Rémi Flamary.



# What is a kernel ?

### Measuring similarities between objects

- ► Two "objects" **x**, **y** in **an abstract space** *X*.
- A kernel aims at measuring "how similar" is x from y.
- e.g.  $\mathcal{X} = \mathbb{R}^d$ , kernel $(\mathbf{x}, \mathbf{y}) = \langle \mathbf{x}, \mathbf{y} \rangle$  or cosine similarity.



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### ML with kernels

- ML methods based on pairwise comparisons.
- By imposing constraints on the kernel (positive definite), we obtain a general framework for learning from data (RKHS).
- + without making any assumptions regarding the type of data (vectors, strings, graphs, images, ...)

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### A principle method for ERM

 $\min_{f \in ?} \frac{1}{n} \sum_{i=1}^{n} \ell(\mathbf{y}_i, f(\mathbf{x}_i)) \to \text{ look for } f \text{ in specific space (RKHS)}$ 

## A feature map $\Phi : \mathcal{X} \to \mathcal{H}$

### From feature map to functions: motivating example

• Feature map can be used to define functions from  $\mathcal{X}$  to  $\mathbb{R}$ .

$$\Phi : \mathbb{R}^2 \to \mathbb{R}^3 = \mathcal{H}$$
$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \mapsto \Phi(\mathbf{x}) = \begin{bmatrix} x_1 \\ x_2 \\ x_1x_2 \end{bmatrix} \text{ and } f(\mathbf{x}) = a \cdot x_1 + b \cdot x_2 + c \cdot x_1 x_2 \ (\mathbb{R}^2 \to \mathbb{R})$$

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• Consider  $\boldsymbol{\theta} = (a, b, c)^{\top} \in \mathbb{R}^3$  then  $f(\mathbf{x}) = \langle \boldsymbol{\theta}, \Phi(\mathbf{x}) \rangle$ .

• Evaluation of f at x is an inner product in feature space.

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 then  $f(\mathbf{x}) = \langle \boldsymbol{\theta}, \Phi(\mathbf{x}) \rangle$ .

• Evaluation of f at x is an inner product in feature space.

Go into higher dimensions to **linearly** separate the classes !



#### Kernels in Machine Learning

#### A bit of kernels theory

Back to machine learning: the representer theorem

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## The definition

### Positive definite (PD) kernel

Let  $\mathcal{X}$  be some space. A function  $\kappa : \mathcal{X} \times \mathcal{X} \mapsto \mathbb{R}$  is a PD kernel if

• It is symmetric 
$$\kappa(\mathbf{x}, \mathbf{y}) = \kappa(\mathbf{y}, \mathbf{x})$$
.

For any  $\mathbf{x}_1, \cdots, \mathbf{x}_n \in \mathcal{X}$  and  $c_1, \cdots, c_n \in \mathbb{R}$ 

$$\sum_{i,j=1}^{n} c_i c_j \kappa(\mathbf{x}_i, \mathbf{x}_j) \ge 0.$$
 (1)

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#### Remarks

- ► (1) equiv.  $\mathbf{K} := (\kappa(\mathbf{x}_i, \mathbf{x}_j))_{ij} \in \mathbb{R}^{n \times n}$  is a PSD matrix  $\forall \mathbf{x}_1, \cdots, \mathbf{x}_n \in \mathcal{X}$ .
- For  $\kappa(\mathbf{x}, \mathbf{y}) = \langle \mathbf{x}, \mathbf{y} \rangle$  if  $\mathbf{X} = (\mathbf{x}_1, \cdots, \mathbf{x}_n)^{\top}$  then  $\mathbf{c}^{\top} \mathbf{K} \mathbf{c} = \|\mathbf{X}^{\top} \mathbf{c}\|_2^2 \ge 0$ .
- Works also for  $\kappa(\mathbf{x}, \mathbf{y}) = \langle \Phi(\mathbf{x}), \Phi(\mathbf{y}) \rangle$  for any  $\Phi$ .
- ► Not entirely obvious  $\kappa(\mathbf{x}, \mathbf{y}) = \exp(-\|\mathbf{x} \mathbf{y}\|_2^2/2\sigma^2)$ . (see TD)

## Basic properties (see TD)

Let  $\kappa_1, \kappa_2, \cdots$  be fixed PD kernels.

- $\gamma \kappa_1$  for any  $\gamma > 0$  is a PD kernel.
- $\blacktriangleright$   $\kappa_1 + \kappa_2$  is a PD kernel.
- ►  $\kappa(\mathbf{x}, \mathbf{y}) := \lim_{n \to +\infty} \kappa_n(\mathbf{x}, \mathbf{y})$  is a PD kernel (provided it exists).

• 
$$\kappa(\mathbf{x}, \mathbf{y}) := \kappa_1(\mathbf{x}, \mathbf{y}) \kappa_2(\mathbf{x}, \mathbf{y})$$
 is a PD kernel.

▶ If  $f : \mathcal{X} \to \mathbb{R}$  then  $\kappa(\mathbf{x}, \mathbf{y}) := f(\mathbf{x})\kappa_1(\mathbf{x}, \mathbf{y})f(\mathbf{y})$  is a PD kernel.

# **Changing the features**



## **Changing the features**



# Polynomial kernel Consider $\Phi : \mathbb{R}^2 \to \mathbb{R}^3$ defined by $\Phi(\mathbf{x} = (x_1, x_2)) = (x_1^2, \sqrt{2}x_1x_2, x_2^2)$ . Then:

$$\kappa(\mathbf{x},\mathbf{y}) := \langle \Phi(\mathbf{x}), \Phi(\mathbf{y}) 
angle_{\mathbb{R}^3} = \cdots = (\langle \mathbf{x}, \mathbf{y} 
angle_{\mathbb{R}^2})^2 \,.$$

Basic properties show that it defines a PD kernel.

## **Changing the features**



#### Polynomial kernel

Consider  $\Phi : \mathbb{R}^2 \to \mathbb{R}^3$  defined by  $\Phi(\mathbf{x} = (x_1, x_2)) = (x_1^2, \sqrt{2}x_1x_2, x_2^2)$ . Then:

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Basic properties show that it defines a PD kernel.

• More generally 
$$\kappa(\mathbf{x}, \mathbf{y}) = \langle \mathbf{x}, \mathbf{y} \rangle^m$$
.

## Translation invariant kernels

A generic form of kernel on  $\mathcal{X} = \mathbb{R}^d$ 

For  $\kappa_0 : \mathbb{R}^d \to \mathbb{R}$ , kernel defined by

$$\kappa(\mathbf{x}, \mathbf{y}) = \kappa_0(\mathbf{x} - \mathbf{y})$$

- e.g. Gaussian kernel  $\kappa(\mathbf{x}, \mathbf{y}) = \exp(-\|\mathbf{x} \mathbf{y}\|_2^2/(2\sigma^2)).$
- ► Recall Fourier transform:  $\widehat{f}(\omega) = \int_{\mathbb{R}^d} f(\mathbf{x}) e^{-i\langle \omega, \mathbf{x} \rangle} d\mathbf{x}$ .
- Based on Bochner's theorem (see Wendland 2004, Theorem 6.11):
  - $\kappa$  is a PD kernel  $\iff orall \omega \in \mathbb{R}^d, \widehat{\kappa_0}(\omega) \geq 0$



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## Main property of PD kernel

Main property: Moore-Aronszajn theorem Aronszajn 1950

A function  $\kappa : \mathcal{X} \times \mathcal{X} \to \mathbb{R}$  is a PD kernel if and only if **there exists a Hilbert space**  $\mathcal{H}$  and **a mapping**  $\Phi : \mathcal{X} \to \mathcal{H}$  such that

 $\forall \mathbf{x}, \mathbf{y} \in \mathcal{X}, \ \kappa(\mathbf{x}, \mathbf{y}) = \langle \Phi(\mathbf{x}), \Phi(\mathbf{y}) \rangle_{\mathcal{H}} \,.$ 

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angle_{\mathcal{H}}.$$



### Some reminders

- $\label{eq:constraint} \boldsymbol{\triangleright} \ \langle \cdot, \cdot \rangle_{\mathcal{H}} : \mathcal{H} \times \mathcal{H} \to \mathbb{R} \text{ is a bilinear, symmetric and such that } \langle \boldsymbol{x}, \boldsymbol{x} \rangle_{\mathcal{H}} > 0 \\ \text{ for any } \boldsymbol{x} \neq 0.$
- A vector space endowed with an inner product is called pre-Hilbert. It is endowed with ||x||<sub>H</sub> := √⟨x, x⟩<sub>H</sub>.
- A Hilbert space is a pre-Hilbert space complete for the norm defined by the inner product.

#### Proof of the theorem in the discrete case

# On the board

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Complete proof Steinwart and Christmann 2008, Theorem 4.16.



### The feature map $\Phi$ and feature space ${\cal H}$

- The feature space may have **infinite dimension** and is **not unique**.
- Polynomial kernel in 2D  $\kappa(\mathbf{x}, \mathbf{y}) = (\langle \mathbf{x}, \mathbf{y} \rangle)^2$ :

$$\Phi(\mathbf{x} = (x_1, x_2)) = (x_1^2, x_2^2, x_1 x_2, x_1 x_2), \ \mathcal{H} = \mathbb{R}^4$$



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 Polynomial kernel in 2D κ(x, y) = ((x, y))<sup>2</sup>:

$$\Phi(\mathbf{x} = (x_1, x_2)) = (x_1^2, x_2^2, x_1x_2, x_1x_2), \ \mathcal{H} = \mathbb{R}^4$$

Another possibility:

$$\Phi(\mathbf{x} = (x_1, x_2)) = (x_1^2, x_2^2, \sqrt{2}x_1x_2), \ \mathcal{H} = \mathbb{R}^3$$



The feature map  $\Phi$  and feature space  ${\cal H}$ 

- The feature space may have **infinite dimension** and is **not unique**.
- Gaussian Kernel in 1D  $\kappa(x, y) = \exp(-|x y|_2^2/(2\sigma^2))$ :

$$\Phi(x) = e^{-\frac{x^2}{2\sigma^2}} \left(1, \sqrt{\frac{1}{1!\sigma^2}}x, \sqrt{\frac{1}{2!\sigma^4}}x^2, \sqrt{\frac{1}{3!\sigma^6}}x^3, \cdots\right)^\top \text{(Taylor series)}$$



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 Gaussian Kernel in 1D κ(x, y) = exp(-|x - y|<sup>2</sup>/(2σ<sup>2</sup>)):

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• Or  $\mathcal{H} = L_2(\mathbb{R})$  using  $\kappa(x, y) = \frac{1}{\sigma} \sqrt{\frac{2}{\pi}} \int_{-\infty}^{+\infty} \exp(-\frac{(x-t)^2}{\sigma^2}) \exp(-\frac{(y-t)^2}{\sigma^2}) dt$ :

$$\Phi(x) = t \rightarrow \frac{2^{\frac{1}{4}}}{\sqrt{\sigma}\pi^{\frac{1}{4}}} \exp(-\frac{(x-t)^2}{\sigma^2})$$

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#### From kernels to functions: first idea

- Given  $\mathcal{H}$  and  $\Phi : \mathcal{X} \to \mathcal{H}_0$ : defines a kernel  $\kappa(\mathbf{x}, \mathbf{y}) = \langle \Phi(\mathbf{x}), \Phi(\mathbf{y}) \rangle_{\mathcal{H}_0}$
- And a space of functions from  $\mathcal{X}$  to  $\mathbb{R}$ .

$$\mathcal{H} := \{f: \exists oldsymbol{ heta} \in \mathcal{H}_0, orall \mathbf{x} \in \mathcal{X}, f(\mathbf{x}) = \langle oldsymbol{ heta}, \Phi(\mathbf{x}) 
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Endowed with the norm

$$\|f\|_{\mathcal{H}} := \inf\{\|\theta\|_{\mathcal{H}_0} : \theta \in \mathcal{H}_0 \text{ with } f = \langle \theta, \Phi(\cdot) \rangle_{\mathcal{H}_0}\}$$
(2)

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• It is a Hilbert space of functions called the RKHS of  $\kappa$ .

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#### From kernels to functions: second idea

- Given a PSD kernel  $\kappa : \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ .
- ▶ 1°) Find a "suitable" (Φ, ℋ) such that κ(x, y) = ⟨Φ(x), Φ(y)⟩<sub>ℋ</sub> (recall: many possible)
- ► 2°) Build upon it to define a suitable space of functions.

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- ► 2°) Build upon it to define a suitable space of functions. (**RKHS**).

### Let $\kappa$ be fixed

- Among all (Φ, H) mentioned in Aronszjan's theorem one H, called RKHS, is of interest to us.
- This is a space of functions from  $\mathcal{X}$  to  $\mathbb{R}$ .
- $\blacktriangleright$  Each data point  $x \in \mathcal{X}$  will be represented by a function given by the canonical feature map

$$\Phi(\mathbf{x}) = \kappa(\cdot, \mathbf{x}) : \mathcal{X} \to \mathbb{R}$$

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#### Example

Consider X = ℝ we could decide to represent x ∈ ℝ as a Gaussian function centered at x:

$$\Phi(x) = y \to \exp(-(x-y)^2/(2\sigma^2))$$

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► What is the corresponding space H (if it exists)? What would be the inner-product?

### Reproducing kernel and RKHS

Let  $\mathcal{H}$  be a **Hilbert space** of functions from  $\mathcal{X}$  to  $\mathbb{R}$  with inner product  $\langle \cdot, \cdot \rangle_{\mathcal{H}}$ .  $\kappa : \mathcal{X} \times \mathcal{X} \to \mathbb{R}$  is called a **reproducing kernel** of  $\mathcal{H}$  if

$$\forall \mathbf{x} \in \mathcal{X}, \kappa(\cdot, \mathbf{x}) \in \mathcal{H}$$

•  $\kappa$  satisfies the reproducing property: for any  $f \in \mathcal{H}$ ,

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If a reproducing kernel of  $\mathcal{H}$  exists, then  $\mathcal{H}$  is called a **RKHS**.

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#### Important properties

- If  $\mathcal{H}$  is a RKHS, then it has a unique reproducing kernel  $\kappa$ .
- (the feature map is not unique only the kernel is)
- A function  $\kappa$  can be the reproducing kernel of at most one RKHS.

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#### **RKHS** and feature spaces

Let  $\mathcal{H}$  be a RKHS with reproducing kernel  $\kappa$ . Then  $\mathcal{H}$  is **one** feature space associated to  $\kappa$ , where the feature map is  $\forall \mathbf{x} \in \mathcal{X}, \Phi(\mathbf{x}) = \kappa(\cdot, \mathbf{x})$ .

So far these functions are a little bit abstract:

#### Two questions

- Given a PD kernel  $\kappa$  what is the RKHS associated to  $\kappa$  ?
- Given a function space, is it a RKHS and what is the reproducing kernel ?

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### Battery of examples

• (on the board) The RKHS associated to  $\kappa(\mathbf{x}, \mathbf{y}) = \langle \mathbf{x}, \mathbf{y} \rangle$  is

$$\mathcal{H} = \{ f_{\boldsymbol{\theta}} = \mathbf{x} \to \langle \boldsymbol{\theta}, \mathbf{x} \rangle; \boldsymbol{\theta} \in \mathbb{R}^d \}$$

endowed with the dot product  $\langle f_{\theta_1}, f_{\theta_2} \rangle_{\mathcal{H}} := \langle \theta_1, \theta_2 \rangle$ .

- (homework) What is the RKHS associated to  $\kappa(\mathbf{x}, \mathbf{y}) = \langle \mathbf{x}, \mathbf{y} \rangle^2$ ?
- The space  $L_2(\mathbb{R}^d)$  is not a RKHS.

## **Examples of RKHS**

#### Battery of examples

The Paley-Wiener space (bandwidth limited Fourier transform):

$$\mathcal{F}_{\pi} := \{f \in L_2(\mathbb{R}) : \operatorname{supp} \hat{f} \in [-\pi, \pi]\}$$

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where  $\hat{f}$  is the Fourier transform of f.

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where  $\hat{f}$  is the Fourier transform of f.

Inverse Fourier transform

$$f(t) = rac{1}{\sqrt{2\pi}} \int_{-\pi}^{\pi} \hat{f}(\omega) e^{i\omega t} \mathrm{d}\omega = \langle \hat{f}, \omega 
ightarrow rac{e^{-i\omega t}}{\sqrt{2\pi}} 
angle_{L_2([-\pi,\pi])}$$

Plancherel-Parseval theorem

$$orall t \in \mathbb{R}, \ f(t) = \langle \hat{f}, \omega 
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• The kernel  $\kappa(s, t) = \frac{\sin(\pi(s-t))}{\pi(s-t)}$ 

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$$f(t) = \frac{1}{\sqrt{2\pi}} \int_{-\pi}^{\pi} \hat{f}(\omega) e^{i\omega t} d\omega = \langle \hat{f}, \omega \to \frac{e^{-i\omega t}}{\sqrt{2\pi}} \rangle_{L_2([-\pi,\pi])}$$

Plancherel-Parseval theorem

$$\forall t \in \mathbb{R}, \ f(t) = \langle \hat{f}, \omega \to \frac{e^{-i\omega t}}{\sqrt{2\pi}} \rangle_{L_2([-\pi,\pi])} = \langle f, \frac{\sin(\pi(\cdot - t))}{\pi(\cdot - t)} \rangle_{L_2(\mathbb{R})}$$

• The kernel 
$$\kappa(s, t) = \frac{\sin(\pi(s-t))}{\pi(s-t)}$$
### Battery of examples

▶ Translation invariant PD kernels on  $\mathbb{R}^d \kappa(\mathbf{x}, \mathbf{y}) = \kappa_0(\mathbf{x} - \mathbf{y})$  with  $\kappa_0 \in L_1(\mathbb{R}^d) \cap C(\mathbb{R}^d)$  and  $\forall \boldsymbol{\omega} \in \mathbb{R}^d, \hat{\kappa_0}(\boldsymbol{\omega}) \ge 0$ .

#### Battery of examples

- ▶ Translation invariant PD kernels on  $\mathbb{R}^d \kappa(\mathbf{x}, \mathbf{y}) = \kappa_0(\mathbf{x} \mathbf{y})$  with  $\kappa_0 \in L_1(\mathbb{R}^d) \cap C(\mathbb{R}^d)$  and  $\forall \boldsymbol{\omega} \in \mathbb{R}^d, \widehat{\kappa_0}(\boldsymbol{\omega}) \ge 0$ .
- The corresponding RKHS is

$$\mathcal{H} = \{ f \in L_2(\mathbb{R}^d) \cap C(\mathbb{R}^d) : \hat{f} / \sqrt{\hat{\kappa_0}} \in L_2(\mathbb{R}^d) \}$$

The inner product is given by:

$$\langle f,g 
angle_{\mathcal{H}} := (2\pi)^{-d/2} \int_{\mathbb{R}^d} \frac{\widehat{f}(\omega)\overline{\widehat{g}(\omega)}}{\widehat{\kappa_0}(\omega)} \mathrm{d}\omega \,.$$

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- ▶ Special case: Matèrn kernel  $\widehat{\kappa_0}(\boldsymbol{\omega}) \propto (\alpha^2 + \|\boldsymbol{\omega}\|_2^2)^{-s}, s > d/2$
- Sobolev spaces of order s: ||f||<sup>2</sup><sub>H</sub> = smoothness of the functions as its derivatives in L<sub>2</sub>(ℝ<sup>d</sup>).

# **Reproducing Kernel Hilbert Space (RKHS)**

### Reproducing kernels are PD kernels

A function  $\kappa : \mathcal{X} \times \mathcal{X} \to \mathbb{R}$  is a reproducing kernel if and only if it is a PD kernel.

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### Remarks

- One direction easy: a reproducing kernel is a PD kernel (on the board).
- ► The other more work: use Moore–Aronszajn theorem + *F* + Steinwart and Christmann 2008, Theorem 4.21.

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#### Important consequence

- Any PSD kernel defines a Hilbert space of functions from  $\mathcal{X}$  to  $\mathbb{R}$ .
- These functions satisfy

$$\forall \mathbf{x} \in \mathcal{X}, \ f(\mathbf{x}) = \langle f, \kappa(\cdot, \mathbf{x}) \rangle_{\mathcal{H}}.$$

Abstract view of H:

$$\mathcal{H} = \overline{\mathsf{Span}\{\kappa(\cdot, \mathbf{x}); \mathbf{x} \in \mathcal{X}\}}.$$

#### Kernels in Machine Learning

A bit of kernels theory

Back to machine learning: the representer theorem

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#### Kernels for structured data

Basics of graphs-kernels Focus on Weisfeler-Lehman Kernel Conclusion

# **Recap on supervised ML**



### Supervised learning

- ► The dataset contains the samples (x<sub>i</sub>, y<sub>i</sub>)<sup>n</sup><sub>i=1</sub> where x<sub>i</sub> is the feature sample and y<sub>i</sub> ∈ 𝔅 its label.
- Prediction space *Y* can be:
  - $\mathcal{Y} = \{-1, 1\}$  or  $\mathcal{Y} = \{1, \dots, K\}$  for classification problems.
  - $\mathcal{Y} = \mathbb{R}$  for regression problems ( $\mathbb{R}^{p}$  for multi-output regression).

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### Minimizing the averaged error on the training data

To find  $f : \mathcal{X} \to \mathcal{Y}$  the idea is to minimize:

$$\min_{f} \frac{1}{n} \sum_{i=1}^{n} \ell(y_i, f(\mathbf{x}_i)) + \lambda \operatorname{Reg}(f)$$
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- How to properly regularize ?
- How to efficiently minimize the quantity ?

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### One solution

- When  $\mathcal{Y} \subset \mathbb{R}$  we can consider  $f \in \mathcal{H}$  where  $\mathcal{H}$  is a RKHS.
- A natural candidate  $\operatorname{Reg}(f) = ||f||_{\mathcal{H}}^2$ : the higher the smoother f is.
- How to ensure that this is not so difficult ?

Suppose  $\mathcal{X} = \mathbb{R}^d$  and  $\mathcal{H}$  a RKHS. Consider ERM

$$\min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^{n} \ell(y_i, f(\mathbf{x}_i)) + \lambda \|f\|_{\mathcal{H}}^2$$

Since 
$$f \in \mathcal{H}$$
, then  $f(\mathbf{x}) = \langle f, \kappa(\cdot, \mathbf{x}) \rangle_{\mathcal{H}} = \langle f, \Phi(\mathbf{x}) \rangle_{\mathcal{H}}$ .

Rewriting ERM in RKHS as

$$\min_{\boldsymbol{\theta}\in\mathcal{H}} \frac{1}{n} \sum_{i=1}^{n} \ell(\mathbf{y}_i, \langle \boldsymbol{\theta}, \boldsymbol{\Phi}(\mathbf{x}_i) \rangle_{\mathcal{H}}) + \lambda \|\boldsymbol{\theta}\|_{\mathcal{H}}^2$$

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## Interpretation of minimization on a RKHS

Suppose  $\mathcal{X} = \mathbb{R}^d$  and  $\mathcal{H}$  a RKHS. Consider ERM

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#### Important interpretation

- $\blacktriangleright$  Then linear classification/regression is made on this high-dim space  ${\cal H}$
- We can deduce the function in low-dim from the high-dim.

## Interpretation of minimization on a RKHS

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Go into higher dimensions to **linearly** separate the classes !



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Go into higher dimensions to **linearly** separate the classes !

- But how to implement  $\Phi(\mathbf{x}) \in \mathcal{H}$  on a computer if dim  $\mathcal{H} = \infty$  ?????
- ► How to solve ERM in *H* ????



## The representer theorem

## Main result

- ▶ Let  $\mathcal{X}$  be any space,  $\mathcal{D} = {\mathbf{x}_1, \cdots, \mathbf{x}_n} \subset \mathcal{X}$  a finite set of points.
- $\mathcal{H}$  a RKHS with reproducing kernel  $\kappa : \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ .
- Let  $\Psi : \mathbb{R}^{n+1} \to \mathbb{R}$  any function that is strictly increasing with respect to the last variable.
- Then any solution f\* of the minimization problem

$$\min_{f\in\mathcal{H}} \Psi(f(\mathbf{x}_1),\cdots,f(\mathbf{x}_n),\|f\|_{\mathcal{H}}^2)$$

can be written as

 $\forall \mathbf{x} \in \mathcal{X}, \ f^{\star}(\mathbf{x}) = \sum_{i=1}^{n} \theta_{i} \kappa(\mathbf{x}, \mathbf{x}_{i}) \text{ for some } \boldsymbol{\theta} \in \mathbb{R}^{n}.$ 

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#### Important remarks

- Although the RKHS can be of infinite dimension any solution lives in Span{κ(·, x₁), · · · , κ(·, xₙ)} which is a subspace of dimension n.
- ► Works for any  $\mathcal{X}$  and  $\Psi = \Psi_0 + g$  with  $g \nearrow !!!$

## Practical use of the representer theorem (1/2)

▶ When the representer theorem holds we can simply look for *f* as

$$orall \mathbf{x} \in \mathcal{X}, \ f(\mathbf{x}) = \sum_{i=1}^n heta_i \kappa(\mathbf{x}, \mathbf{x}_i) ext{ for some } oldsymbol{ heta} \in \mathbb{R}^n$$

Define K := (κ(x<sub>i</sub>, x<sub>j</sub>))<sub>ij</sub>.
 Then , for any j ∈ [n]

$$f(\mathbf{x}_j) = \sum_{i=1}^n \theta_i \kappa(\mathbf{x}_i, \mathbf{x}_j) = [\mathbf{K}\boldsymbol{\theta}]_j.$$

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• Define  $\mathbf{K} := (\kappa(\mathbf{x}_i, \mathbf{x}_j))_{ij}$ . • Then , for any  $j \in \llbracket n \rrbracket$ 

$$f(\mathbf{x}_j) = \sum_{i=1}^n \theta_i \kappa(\mathbf{x}_i, \mathbf{x}_j) = [\mathbf{K}\boldsymbol{\theta}]_j.$$

Also

$$\|f\|_{\mathcal{H}}^{2} = \|\sum_{i=1}^{n} \theta_{i}\kappa(\cdot, \mathbf{x}_{i})\|_{\mathcal{H}}^{2} = \langle \sum_{i=1}^{n} \theta_{i}\kappa(\cdot, \mathbf{x}_{i}), \sum_{j=1}^{n} \theta_{j}\kappa(\cdot, \mathbf{x}_{j}) \rangle_{\mathcal{H}}$$
$$= \sum_{ij} \theta_{i}\theta_{j}\langle\kappa(\cdot, \mathbf{x}_{i}), \kappa(\cdot, \mathbf{x}_{j})\rangle_{\mathcal{H}} = \sum_{ij} \theta_{i}\theta_{j}\kappa(\mathbf{x}_{i}, \mathbf{x}_{j})$$
$$= \boldsymbol{\theta}^{\top} \mathbf{K} \boldsymbol{\theta} .$$

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## Practical use of the representer theorem (2/2)

Therefore the problem

$$\min_{f\in\mathcal{H}} \Psi(f(\mathbf{x}_1),\cdots,f(\mathbf{x}_n),\|f\|_{\mathcal{H}}^2)$$

is equivalent to

$$\min_{\boldsymbol{\theta} \in \mathbb{R}^n} \Psi([\mathbf{K}\boldsymbol{\theta}]_1, \cdots, [\mathbf{K}\boldsymbol{\theta}]_n, \boldsymbol{\theta}^\top \mathbf{K}\boldsymbol{\theta})$$

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- 1°) To tackle it we only need the Gram matrix K: kernel trick !
- ▶ 2°) Can be used whatever  $\mathcal{X}, \kappa$  !
- 3°) We can solve it on a computer since finite dimensional !
- ▶ 4°) It can usually be solved analytically or by numerical methods.

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### Application to ERM

If we look for f in a RKHS then we need to solve

$$\min_{\boldsymbol{\theta} \in \mathbb{R}^n} \frac{1}{n} \sum_{i=1}^n \ell(\mathbf{y}_i, [\mathbf{K}\boldsymbol{\theta}]_i) + \lambda \boldsymbol{\theta}^\top \mathbf{K} \boldsymbol{\theta}$$

Setting

- ▶  $\mathbf{x}_i \in \mathcal{X}$  (not necessarily  $\mathbb{R}^d$  !) and  $y_i \in \mathbb{R}, \mathbf{y} = (y_1, \cdots, y_n)^\top \in \mathbb{R}^n$
- We consider the square loss  $\ell(y, y') = (y y')^2$
- The ERM in the RKHS is

$$\min_{f\in\mathcal{H}} \frac{1}{n} \sum_{i=1}^{n} (y_i - f(\mathbf{x}_i))^2 + \lambda \|f\|_{\mathcal{H}}^2.$$

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## Kernel Ridge Regression

The ERM in the RKHS is equivalent to the minimization problem:

$$\min_{\boldsymbol{\theta} \in \mathbb{R}^n} \frac{1}{n} \| \mathbf{y} - \mathbf{K} \boldsymbol{\theta} \|_2^2 + \lambda \boldsymbol{\theta}^\top \mathbf{K} \boldsymbol{\theta}$$

How can we solve it ? What is the time/memory complexity ?

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## Solution

Given by 
$$\theta^* = (\mathbf{K} + \lambda n \mathbf{I})^{-1} \mathbf{y}, \ \forall \mathbf{x} \in \mathcal{X}, f^*(\mathbf{x}) = \sum_{i=1}^n \theta_i^* \kappa(\mathbf{x}, \mathbf{x}_i).$$

• Gaussian kernel  $\kappa(x, x') = \exp(-|x - x'|^2/(2\sigma^2))$ 

• Regularization parameter  $\lambda$ 



## Kernel ridge regression vs linear regression

• Take  $\mathcal{X} = \mathbb{R}^d$  and the linear kernel  $\kappa(\mathbf{x}, \mathbf{y}) = \langle \mathbf{x}, \mathbf{y} \rangle$ .

▶ Let  $\mathbf{X} = (\mathbf{x}_1, \cdot, \mathbf{x}_n)^\top \in \mathbb{R}^{n \times d}$  the data. The Gram matrix is  $\mathbf{K} = \mathbf{X}\mathbf{X}^\top$ .

Then corresponding function is

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• We have  $\mathbf{w}^* = \mathbf{X}^\top (\mathbf{X}\mathbf{X}^\top + \lambda n \mathbf{I}_n)^{-1} \mathbf{y}$ .

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 $\ell_2$  penalized linear regression: ridge regression The problem

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Matrix inversion lemma

$$(\mathbf{X}^{\top}\mathbf{X} + \lambda n\mathbf{I}_d)^{-1}\mathbf{X}^{\top} = \mathbf{X}^{\top}(\mathbf{X}\mathbf{X}^{\top} + \lambda n\mathbf{I}_n)^{-1}$$

Both agree !

• Complexity roughly: KRR  $O(n^3)$ , RR  $O(\min\{d^3, n^3\})$ .

## **Binary classification**



### Objective

$$(\mathbf{x}_i, y_i)_{i=1}^n \quad \Rightarrow \quad f: \mathbb{R}^d \to \{-1, 1\}$$

Train a function f(x) = y ∈ 𝔅 predicting a binary value (𝔅 = {−1, 1}).
 f(x) = 0 defines the boundary on the partition of the feature space.

### ERM in RKHS

$$\min_{f\in\mathcal{H}} \frac{1}{n} \sum_{i=1}^n \ell(y_i, f(\mathbf{x}_i)) + \lambda \|f\|_{\mathcal{H}}^2.$$

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# Loss functions

## A focus on classification problems $\mathcal{Y} = \{-1,1\}$

 $\ell(y_i, f(\mathbf{x}_i)) = \Phi(y_i f(\mathbf{x}_i))$  with  $\Phi$  non-increasing.

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•  $y_i f(\mathbf{x}_i)$  is the margin.

$$\blacktriangleright \ \ell(y_i, f(\mathbf{x}_i)) = \mathbf{1}_{y_i f(\mathbf{x}_i) \le 0} \ (0/1 \text{ loss})$$

•  $\ell(y_i, f(\mathbf{x}_i)) = \max\{0, 1 - y_i f(\mathbf{x}_i)\}$  (hinge loss: **SVM**)

• 
$$\ell(y_i, f(\mathbf{x}_i)) = \log(1 + e^{-y_i f(\mathbf{x}_i)})$$
 (logistic loss)

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# Support Vector Machines (SVM)

### Definition

▶ The hinge-loss is the function  $\mathbb{R} \to \mathbb{R}_+$ :

$$\Phi_{ ext{hinge}}(x) = \max(1-x,0)$$

$$= \begin{cases} 0 & ext{if } x \geq 1 \\ 1-x & ext{otherwise} \end{cases}$$



Interpretation of the loss  $\ell(y, f(x)) = \Phi_{hinge}(yf(x))$ 

When yf(x) ≥ 0: sign(y) = sign(f(x)) thus good prediction → the loss should be "small".

▶ When 
$$yf(x) \ge 1$$
: if  $y = +1 \implies f(x) \ge 1$ , if  $y = -1 \implies f(x) \le -1 \rightarrow \text{ zero loss is a good idea.}$ 

### Definition

SVM is the corresponding large-margin classifier, which solves:

$$\min_{f \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^{n} \Phi_{\text{hinge}}(y_i f(\mathbf{x}_i)) + \lambda \|f\|_{\mathcal{H}}^2.$$

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Solving for the SVM (details in Steinwart and Christmann 2008)

- Representer theorem: sol. of the form  $f^{\star}(\mathbf{x}) = \sum_{i=1}^{n} \theta_{i}^{\star} \kappa(\mathbf{x}, \mathbf{x}_{i})$ .
- $\theta^*$  can be found by solving a quadratic program (QP).
- Again: we only need to know the Gram matrix  $\mathbf{K} = (\kappa(\mathbf{x}_i, \mathbf{x}_j))_{ij}$ .

# What is SVM doing ?




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SVM finds the hyperplane that maximizes the **margin** 





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- Kernel theory is very rich, kernels are quite simple but also versatile.
- Defines a very general way of learning classifiers/regressors on any kind of space.
- Based on the representer theorem: we only need the Gram matrix !
- Difficulties: the choice of the kernel (see TD), also can be expensive.

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